

Bladed 5

10th November 2016

Ungraded

Bladed 5

Presentation contents

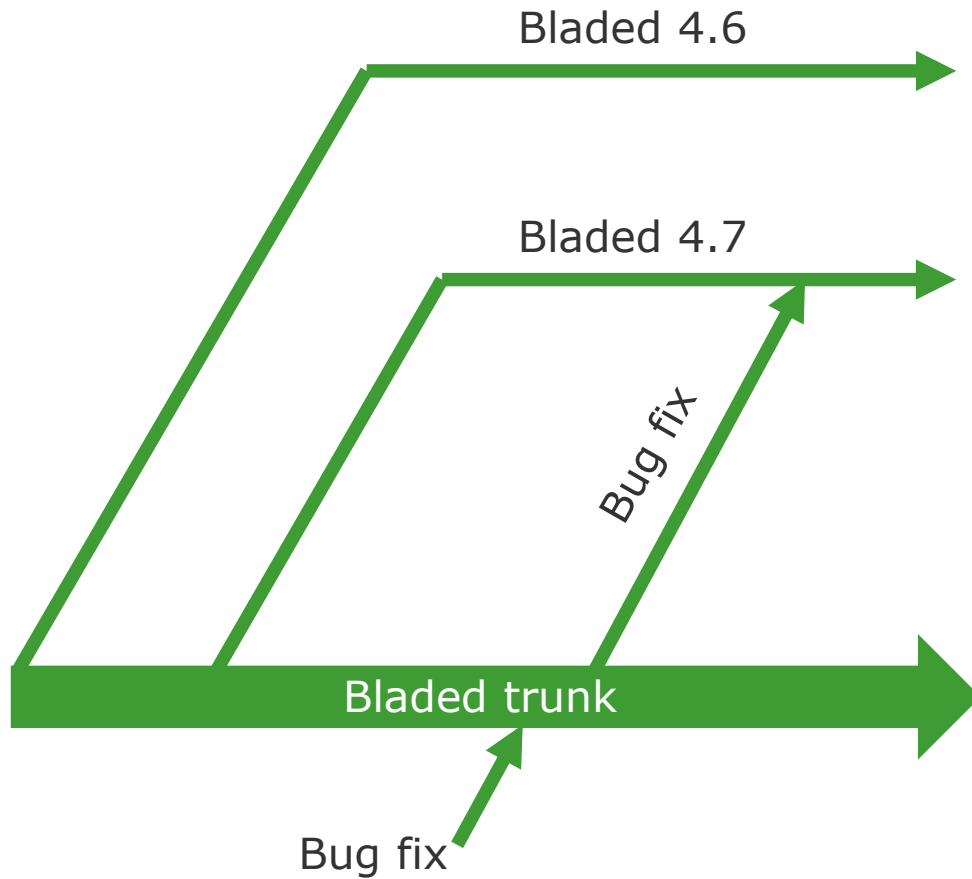
- My understanding of users concerns
- How Bladed is developed and managed
- Changes that we are making
- How this relates to Bladed 5

Key concerns from Bladed Users

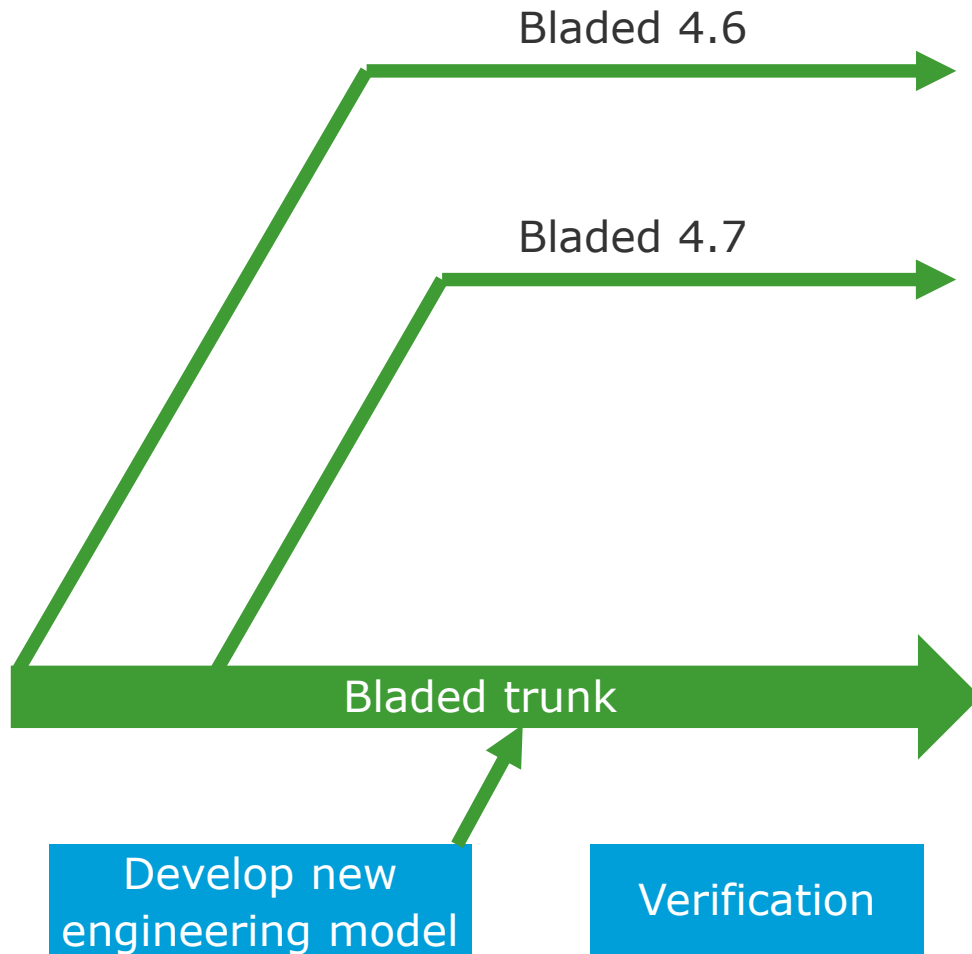
1. Engineering code quality - verification
2. Process improvement
 - Loadset management
 - Automation
 - Batch handling
 - Post-processing
 - Data viewer
3. Ability to deliver small engineering model extensions
4. Results differences in different versions of the code

Can better version management be part of the answer?

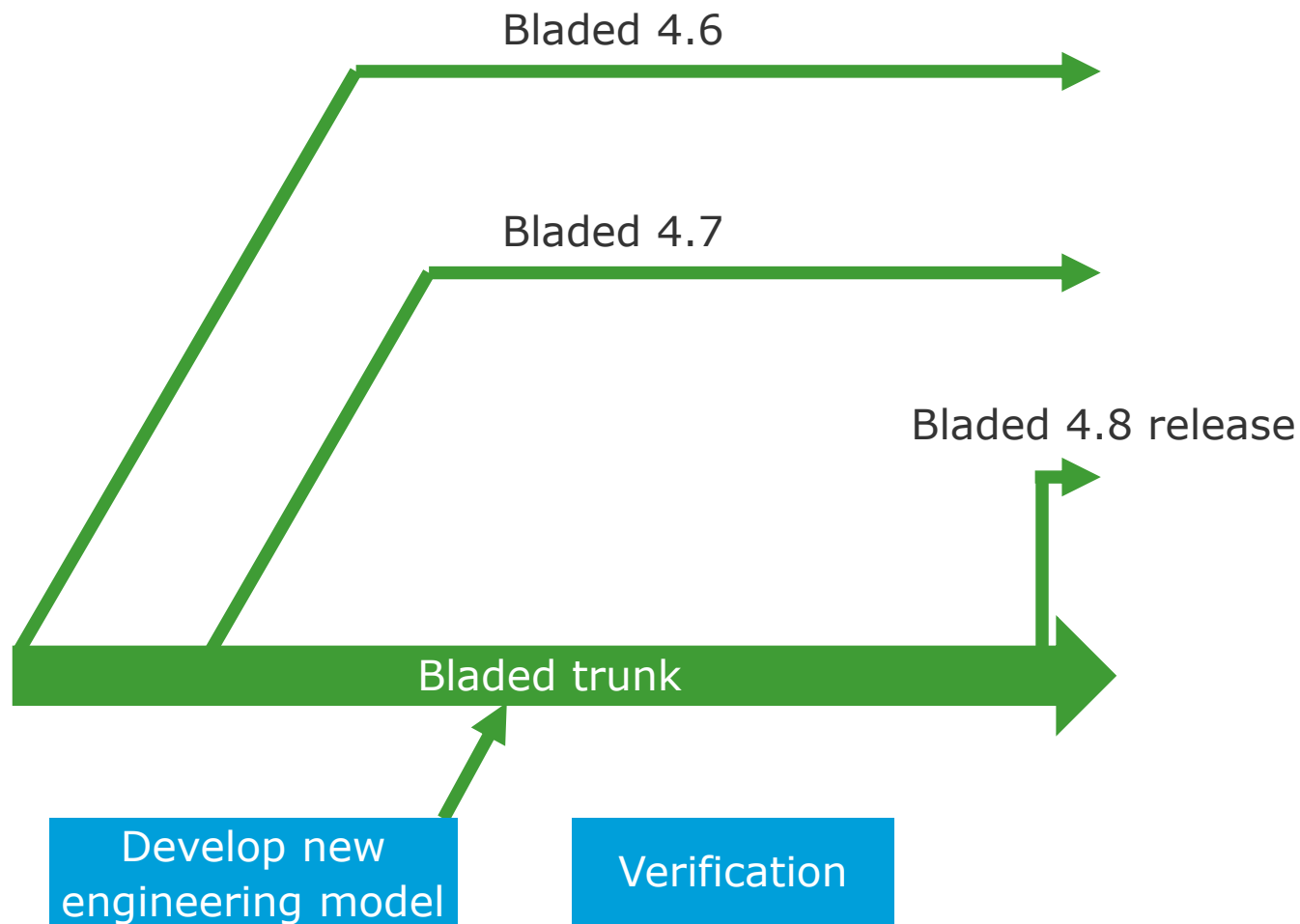
Bladed Version Management – Branching



Bladed Version Management – Branching

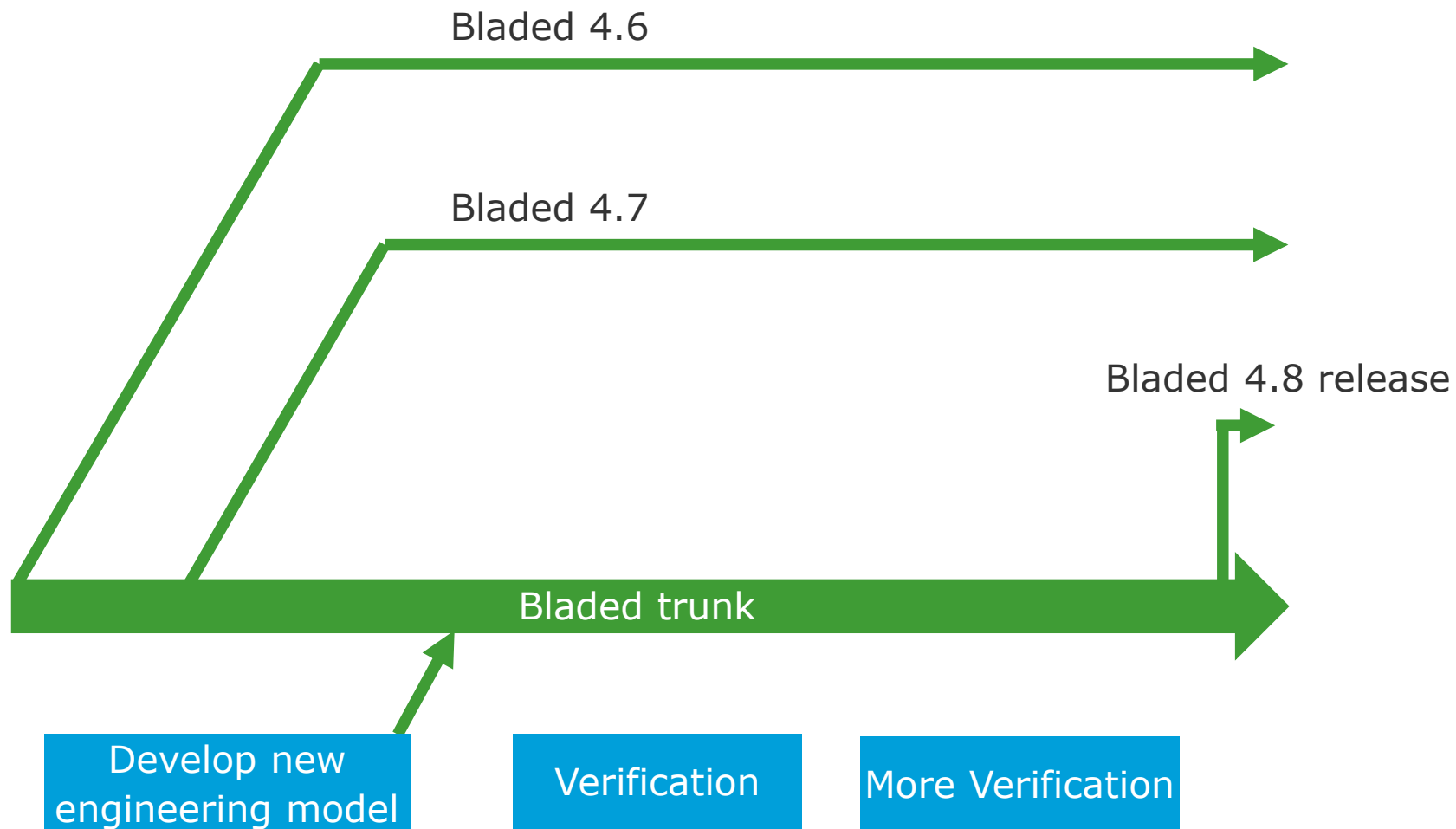


Bladed Version Management – Releasing



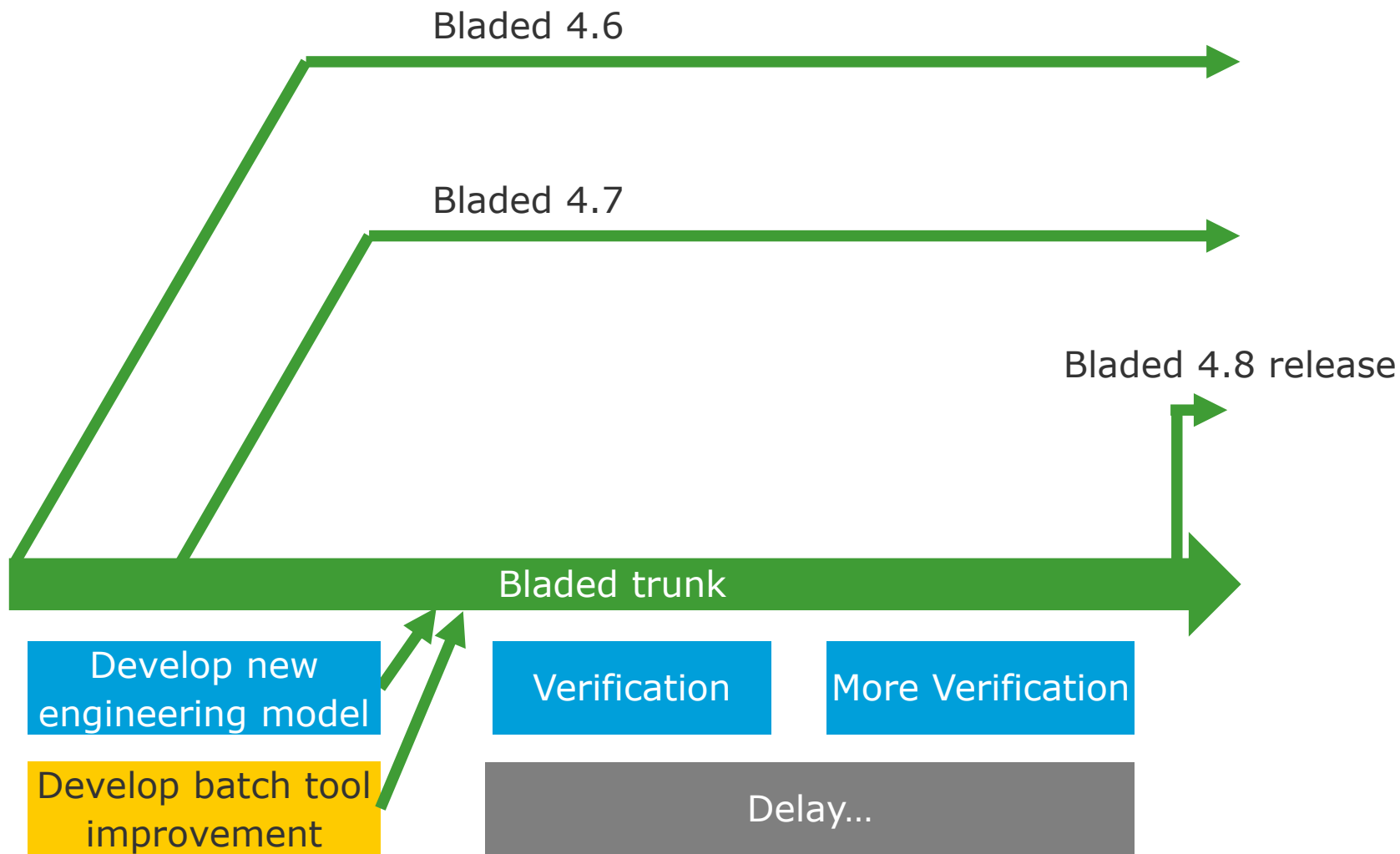
Ungraded

Bladed Version Management – Verification phase



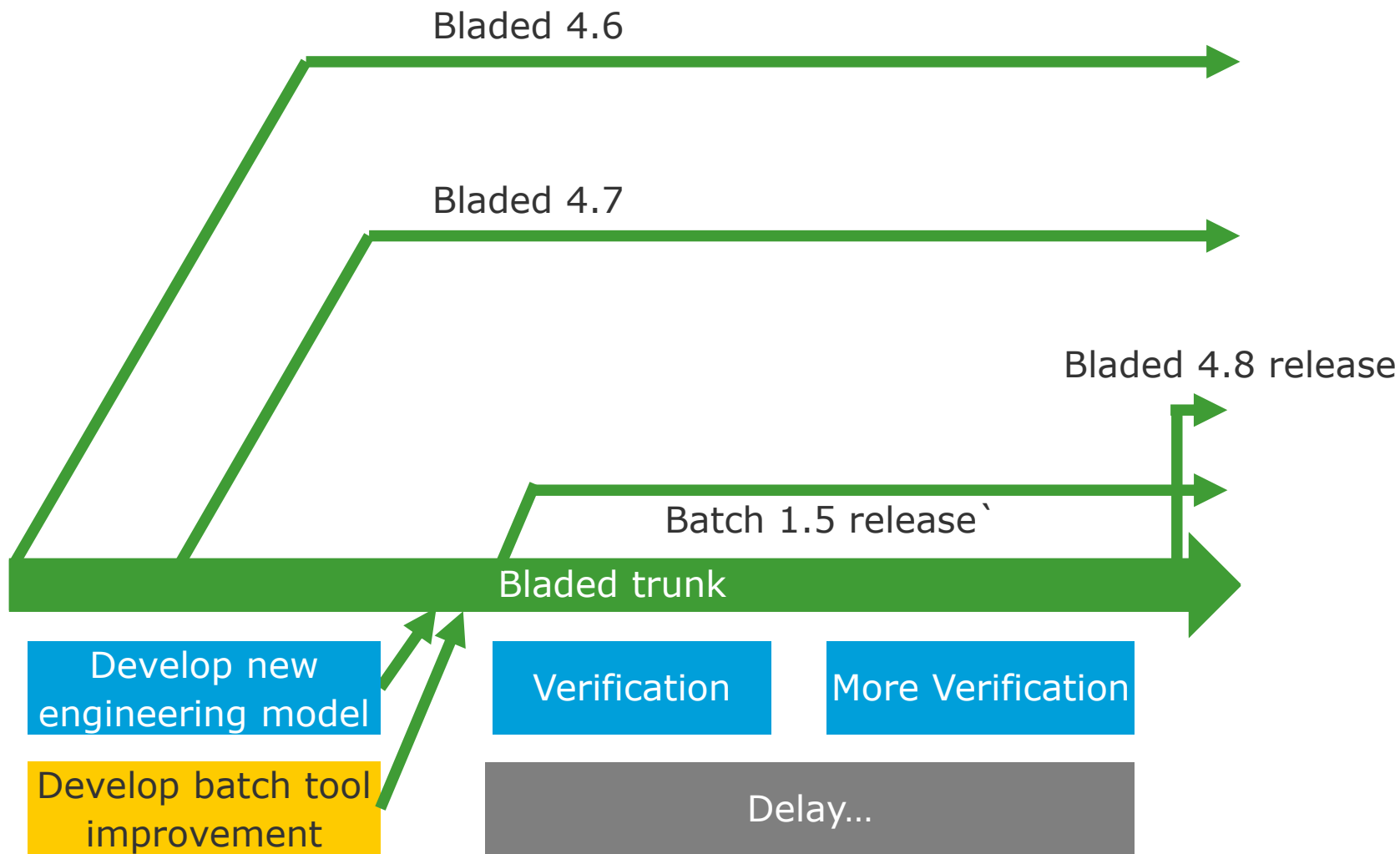
Ungraded

Bladed Version Management – The constraints



Ungraded

Bladed Version Management – Releasing modular tools



Ungraded

Key concerns from Bladed Users

1. Engineering code quality - verification
2. Process improvement
3. Ability to deliver small engineering model extensions
4. Results differences in different versions of the code

Can better version management be part of the answer?

Bladed Version Management – Benefits of separate modular releases

1. Allow more time for verification
2. Reduce delays in releasing completed features
 - Process tools designed for all Bladed versions, not just current

Bladed 4.8 release



4. Verification gives better understanding of results differences
 - Reduce the number of releases – each can be better supported

Develop new engineering model

Verification

More Verification

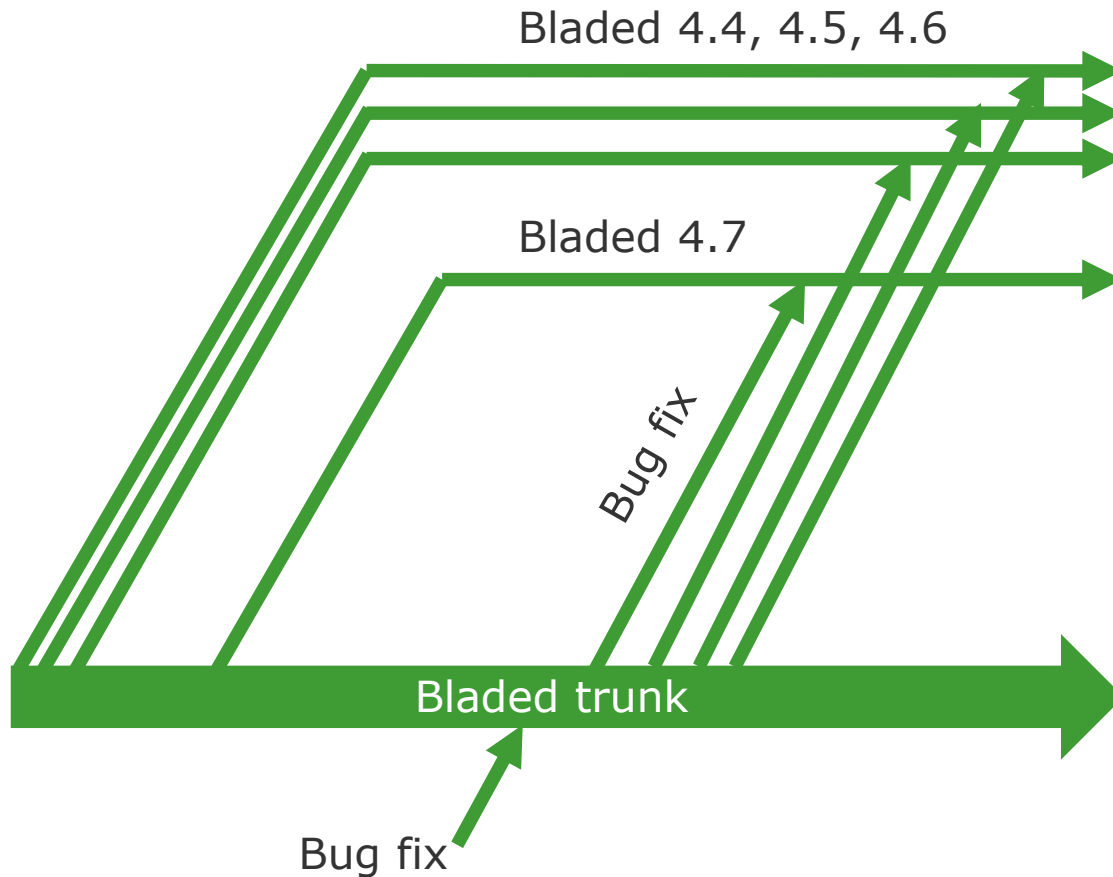
Batch 1.5 release`



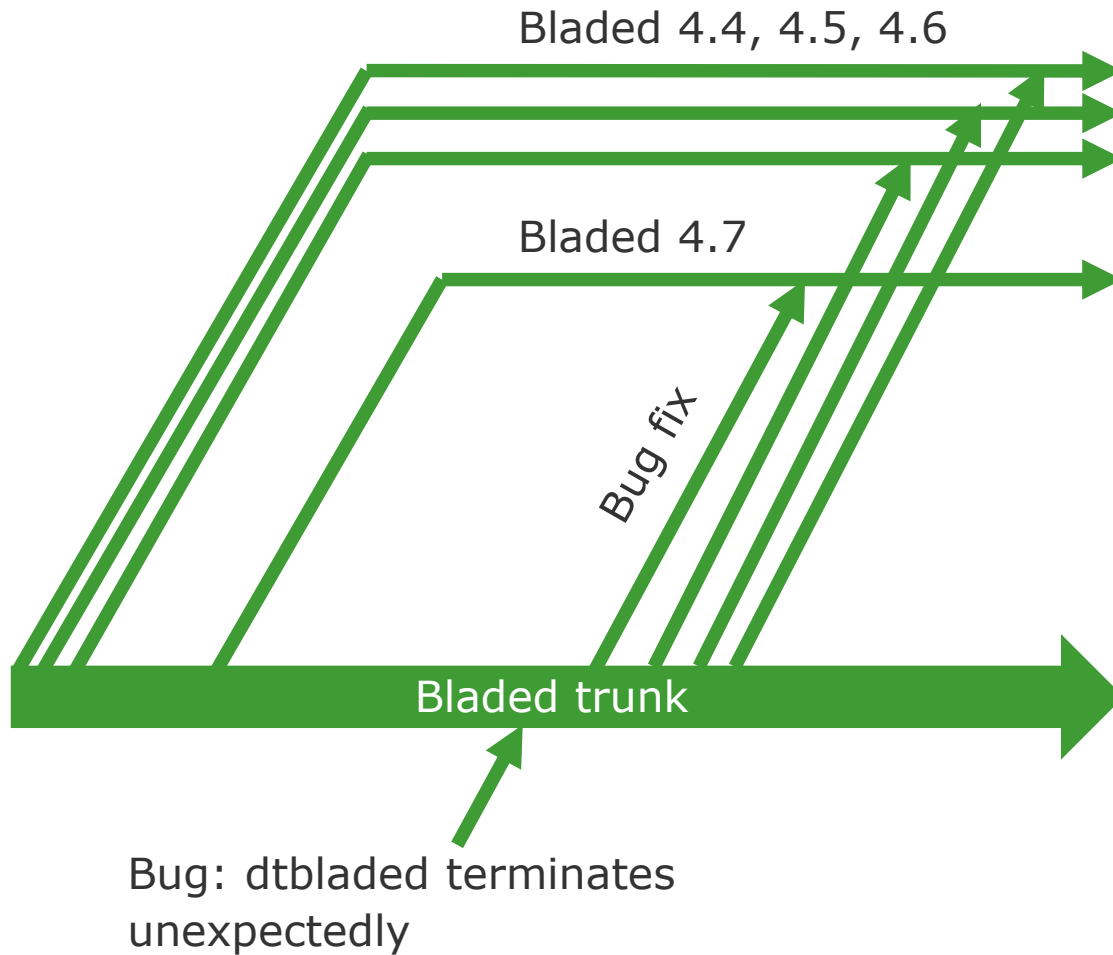
Develop batch tool improvement

Ungraded

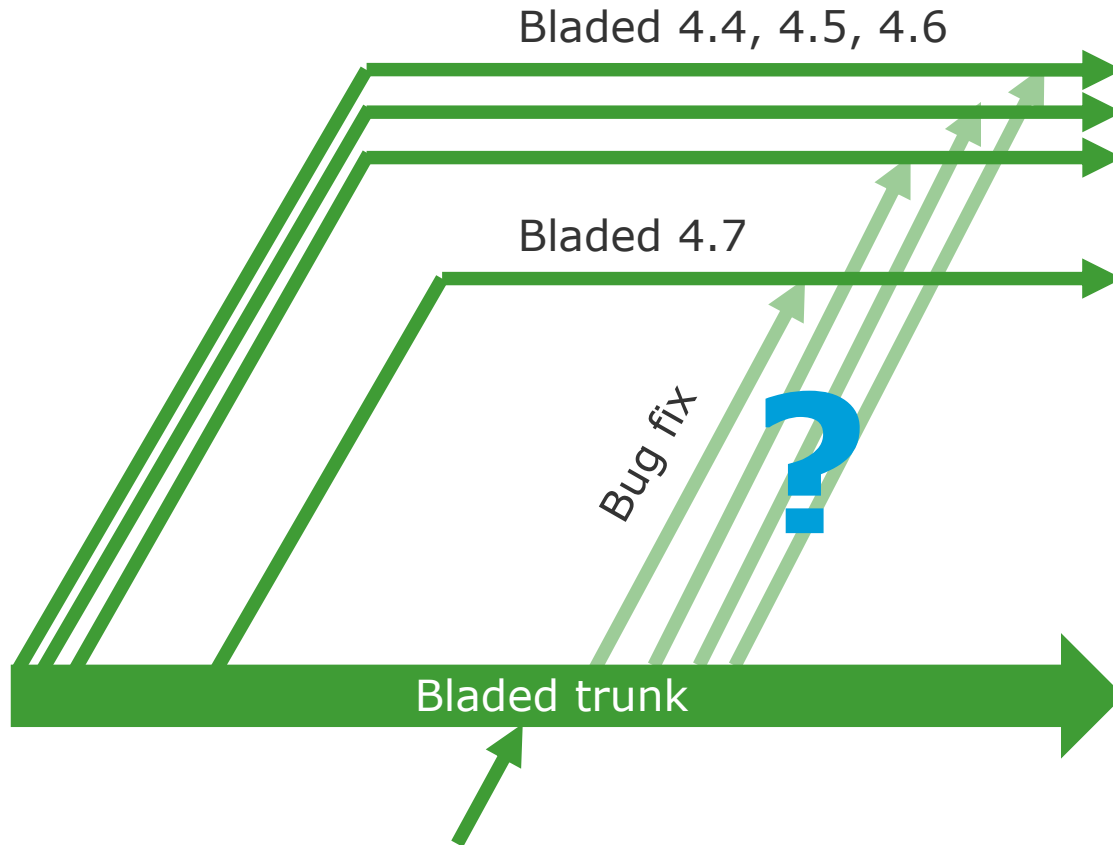
Bladed Version Management – Better supported branches



Bladed Version Management – Better supported branches



Bladed Version Management – Better supported branches



- To maintain consistent results, some defects should be left alone
- Consistency of results should be verified

Bug: correction to
implementation of
calculation

Causes for change in results better documented

Log of known issues.xlsx [Protected View] - Excel Rainey, Patrick James

File Home Insert Page Layout Formulas Data Review View Add-ins TEAM Tell me what you want to do Share

PROTECTED VIEW Be careful—email attachments can contain viruses. Unless you need to edit, it's safer to stay in Protected View. Enable Editing

A22 LM blade load configuration files

	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O	P
1		Version fixed														
2	Fix or new feature	3.85	4	4.1	4.2	4.3	4.4	4.5	4.6	4.7	4.8	Area	Severity	bug or feature	Offshore only	Other subset of models
15	Improved Beddoes Leishman dynamic stall	no	no	no	no	yes	yes	yes	yes	yes	yes			feature	no	
16	Include effect of shear axis orientation	no	no	no	no	no	yes	yes	yes	yes	yes			feature	no	
17	Improved pitch actuator model	no	no	no	no	no	yes	yes	yes	yes	yes			feature	no	
18	Multi-part Blade	no	no	no	no	no	no	no	no	4.7.0.70	yes			feature	no	
19	Improved aerodynamics code	no	no	no	no	no	no	no	no	Beta	yes			feature	no	
20	AQWA flow solver import	no	no	no	no	no	no	no	4.6.0.114	4.7.0.62	yes			bug	yes	Where AQWA data is imported
21	Water partical kinematics at seabed	no	no	no	no	no	no	no	4.6.0.111	4.7.0.54	yes			bug	yes	sea state files only

Intro Known Issues

Ready 100%

Ungraded

Better supported branches – Engineering code additions

- Multi-part Blade was merged down to 4.7
- Pre- and post-processing will be compatible with previous versions
- More verification of consistency of results enables adding engineering code
 - There is an overhead with merging code

Take a step back

Fewer new version releases

More delivered to existing releases

-> We can afford to be more radical with the next new version

Key concerns from Bladed developers

- Prefer code that is built using the latest best practice
 - Prefer code that uses the latest technology
 - Prefer coding using the latest coding tools
-
- They want to be able to extend the code quickly and with low risk
3. Ability to deliver small engineering model extensions
-
- This motivates modernising the current UI

The Bladed 5 design

- Based on the .NET, WPF
- Data model driven design
- Bladed hasn't had a separation between the data model and the VB6 GUI
- That's why it is slow in create a batch from existing runs
 - Only the VB6 *graphical* user interface knew how to convert from a \$pj to a .in file
- Based on UX lead design presented in previous conference by Matt Corral

The Bladed 5 design

Bladed v5.0

File Edit View Window Help

On Off Power production 72 %

Hub

Blade root

Root length	1.25 m
Root diameter	1.9 m
Root drag coefficient	1 m

R-N Assembly

- Rotor 2.5 m
- Hub
- Nacelle

Delta 3 angle 0 deg

Hub

Mass	14000 kg
Centre of mass	0 m
Inertia about shaft	12000 kg/m ²
Inertia perpendicular to shaft	0 kg/m ²

Stator

Inertia about shaft	0 kg/m ²
---------------------	---------------------

Rotor + stator

Mass	0 kg
Centre of mass	0 m
Inertia perpendicular to shaft	0 kg/m ²

Counterweight for 1-blade turbines

Mass	0 kg
Inertia about shaft	0 kg/m ²

Total mass 14135 kg

Centre Auto Solid

1.9 m

1.25 m

2.5 m

CoM -1.3,0,1.6

-23,15,10 Beam 304 None Options

Ungraded

The Bladed 5 design

The screenshot displays the Bladed v5.0 software interface. The left sidebar contains various tool icons. The main window is divided into two panes. The left pane shows the 'Pitch Actuator' configuration panel, which includes several sections: 'Input demand', 'External', 'Actuator dynamic response', and 'Actuators'. The 'Actuators' section is currently selected, showing a list of actuators with checkboxes. The right pane displays a block diagram of the pitch control system.

Pitch Actuator Configuration:

- Input demand**
 - Demand type: Position
 - Point trajectory planning: Inactive
 - Individual pitch control: ☐
- External**
 - External DLL: ☐
 - Track external hardware: ☐
- Actuator dynamic response**
 - Response to position demand: 2nd order passive
- Actuators**
 - Pitch Actuator: ☐
 - Yaw Actuator: ☐
- Actuator parameters**
 - Bearing friction: ☐
 - Drive details: None
 - Single actuator pitch system: ☐
 - Safety system definition: Rate demand
 - Actuator torque / Force limits: Fixed limits
 - Limits: ☐
 - Rate calculated according to: Constant rate
 - Rate demand: 0 deg/s

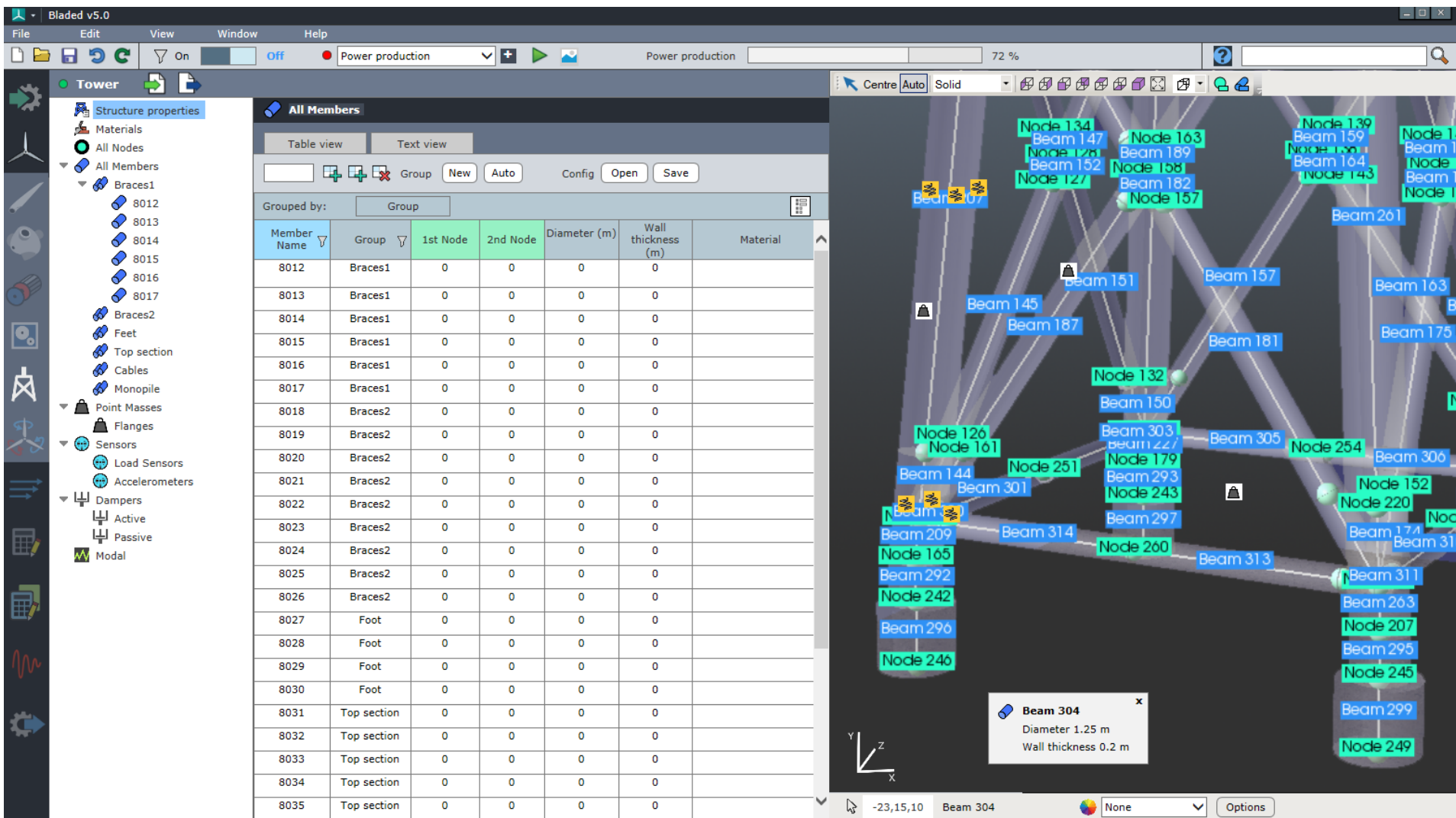
Block Diagram:

```
graph TD; A([Controller Position Demand]) --> B[Transfer Function]; B --> C([Position]); C --> D[Limit Switches]; C --> E[End Stops]; F[Torque Limits] --> B;
```

The block diagram illustrates the pitch control system. It starts with a 'Controller Position Demand' block, which feeds into a 'Transfer Function' block. The 'Transfer Function' block also receives input from 'Torque Limits'. The output of the 'Transfer Function' block is the 'Position' block. The 'Position' block is connected to 'Limit Switches' and 'End Stops'.

Ungraded

The Bladed 5 design



Ungraded

The Bladed 5 Design

